

Dynamic Multiscaling in Turbulence

Dhrubaditya Mitra¹ Rahul Pandit²
Samriddhi Shankar Ray²

¹Département Cassiopée,
Observatoire de la Côte d'Azur,
Nice, France

²Department of Physics
Indian Institute of Science
Bangalore, India.

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Dynamics of Critical phenomenon

- Near a critical point the spin-spin correlation function shows *scaling* and the characteristic correlation length, ξ , diverges.

$$\langle s(\mathbf{x})s(\mathbf{x} + \mathbf{r}) \rangle = \frac{1}{r^{d-2+\eta}} G(|r|/\xi)$$
$$\xi \sim |\mathbb{T} - \mathbb{T}_c|^{-\gamma} \quad \text{as} \quad \mathbb{T} \rightarrow \mathbb{T}_c$$

where η , γ are critical exponents.

- The time-dependent correlation function:

$$\langle s(\mathbf{x}, 0)s(\mathbf{x} + \mathbf{r}, t) \rangle = \langle s(\mathbf{x})s(\mathbf{x} + \mathbf{r}) \rangle f(t/\tau)$$
$$\tau \sim \xi^z$$

where ξ is the dynamic critical exponent.

Turbulence

- Structure functions:

$$\begin{aligned}\delta\phi(\mathbf{x}, \mathbf{r}, t) &\equiv \phi(\mathbf{x} + \mathbf{r}, t) - \phi(\mathbf{x}, t) \\ S_p(\mathbf{r}) &\equiv \langle [\delta\phi]^p \rangle\end{aligned}$$

- In fully developed turbulence, the structure functions show *multiscaling*

$$S_p(\mathbf{r}) \sim r^{\zeta_p}$$

where ζ_p is a nonlinear convex function of p .

- K41 implies $\zeta_p = p/3$.
- How does the dynamic structure functions behave ?

$$\begin{aligned}\mathcal{F}(\mathbf{r}, t) &\equiv \langle \delta\phi(\mathbf{r}, t)\delta\phi(\mathbf{r}, 0) \rangle \\ &= S_p(\mathbf{r})G[t/\tau(\mathbf{r})] \\ \tau(\mathbf{r}) &\sim r^z\end{aligned}$$



Fig. 1.10. Wake behind two identical cylinders at $R = 1800$. Courtesy R. Dumas.

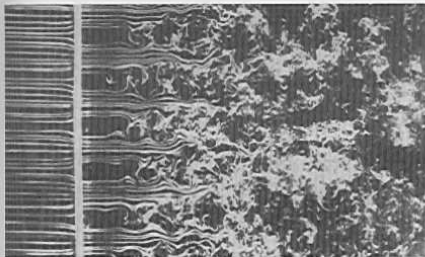


Fig. 1.11. Homogeneous turbulence behind a grid. Photograph T. Corke and H. Nagib.

Measurements are typically done by a single probe. The time-series of velocity is converted to spatial field by Taylor's hypothesis.

Eulerian, Lagrangian and quasi-Lagrangian

- For Eulerian variables : typical time and length scales are linearly related. Hence dynamic scaling exponent $z = 1$. A phenomenon called *sweeping*.
- For Lagrangian quantities, K41 predicts:

$$\tau(\mathbf{r}) \sim \frac{r}{\delta u(\mathbf{r})} \sim r^{2/3}$$
$$z = 2/3$$

- Quasi-Lagrangian velocity is the Eulerian velocity relative to a fluid particle. This is expected to show no sweeping. The equal-time behaviour is **similar** to Eulerian and dynamic behaviour is similar to the Lagrangian velocities.

Dynamics of Lagrangian quantities

- Kraichnan model of passive-scalar
- Multifractal model for fluid turbulence.
- Multifractal model for passive-scalar turbulence.

Kraichnan model of passive scalar

$$\partial_t \theta + (\mathbf{u} \cdot \nabla) \theta = \kappa \nabla^2 \theta + f^\theta,$$

Velocity is random, Gaussian with co-variance

$$\begin{aligned} \langle \mathbf{u}_i(\mathbf{x}, t) \mathbf{u}_j(\mathbf{x} + \ell, t') \rangle &= 2D_{ij}(\ell) \delta(t - t') \\ D_{ij}(\ell) &= D_0 \delta_{ij} - \frac{1}{2} \mathbf{d}_{ij}(\ell) \end{aligned}$$

- $D_0 \sim L^\xi$
- $L \rightarrow \infty$ and $\eta \rightarrow 0$,

$$\mathbf{d}_{ij} = D_1 \ell^\xi \left[(d - 1 + \xi) \delta_{ij} - \xi \frac{\ell_i \ell_j}{\ell^2} \right] \sim \ell^\xi$$

Equal-time statistics

- Multiscaling can be analytically (but **perturbative**) demonstrated.
- $S_p(\ell) \sim \ell^{\zeta_p^0}$.
- $0 < \xi < 2$.
- Structure functions have good limits, not correlation functions.

Dynamic structure functions

$$\begin{aligned}\delta\phi(\mathbf{x}, \mathbf{t}, \mathbf{r}) &\equiv \phi(\mathbf{x} + \mathbf{r}, \mathbf{t}) - \phi(\mathbf{x}, \mathbf{t}) \\ \mathcal{F}_2^\phi(\mathbf{r}, \mathbf{t}) &= \langle [\delta\phi(\mathbf{x}, 0, \mathbf{r})\delta\phi(\mathbf{x}, \mathbf{t}, \mathbf{r})] \rangle \\ &= 2C^\phi(\mathbf{0}, \mathbf{t}) - 2C^\phi(\mathbf{r}, \mathbf{t}) \\ C^\phi(\mathbf{r}, \mathbf{t}) &\equiv \langle \phi(\mathbf{x} + \mathbf{r}, 0)\phi(\mathbf{x}, \mathbf{t}) \rangle\end{aligned}$$

- \mathbf{t} strictly positive.

Dynamic scaling

$$\begin{aligned}\partial_t C^\Phi(\mathbf{r}, t) &= \langle \phi(\mathbf{x} + \mathbf{r}, 0) \partial_t [\phi(\mathbf{x}, t)] \rangle \\ &= -\langle \phi(0) (\mathbf{u} \cdot \nabla) \theta \rangle + \kappa \nabla^2 \langle \phi(0) \phi \rangle + \langle \phi(0) f^\Phi \rangle\end{aligned}$$

$$\partial_t C^\theta(\mathbf{r}, t) = D^0(L) \partial_{ii} C^\theta \sim L^\xi \partial_{ii} C^\theta;$$

$$\partial_t C^{\hat{\theta}}(\mathbf{r}, t) = (D^0 \delta_{ij} - D_{ij}) \partial_{ij} C^{\hat{\theta}} \sim d_{ij}(\mathbf{r}) \partial_{ij} C^{\hat{\theta}}.$$

$$C^\Phi(\mathbf{r}, t) \sim \exp[-t/\tau^\Phi(\mathbf{r})]$$

$$\tau^{\hat{\theta}}(\mathbf{r}, t) = r^{1-\xi}; \tau^\theta(\mathbf{r}, t) = r^2$$

In the limit of $L \rightarrow \infty$, $C^\theta(\mathbf{r}, t)$ diverges for all r .

$z^{\text{ql}} = 2 - \xi$, a **bridge relationship**.

Dynamic scaling

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$$\begin{aligned}\partial_t C^\theta(\mathbf{r}, t) &= D^0(L) \partial_{ii} C^\theta \sim L^\xi \partial_{ii} C^\theta; \\ \partial_t C^{\hat{\theta}}(\mathbf{r}, t) &= (D^0 \delta_{ij} - D_{ij}) \partial_{ij} C^{\hat{\theta}} \sim d_{ij}(\mathbf{r}) \partial_{ij} C^{\hat{\theta}}. \\ C^\Phi(\mathbf{r}, t) &\sim \exp[-t/\tau^\Phi(\mathbf{r})]\end{aligned}$$

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In the limit of $L \rightarrow \infty$, $C^\theta(\mathbf{r}, t)$ diverges for all \mathbf{r} .

$z^{ql} = 2 - \xi$, a **bridge relationship**.

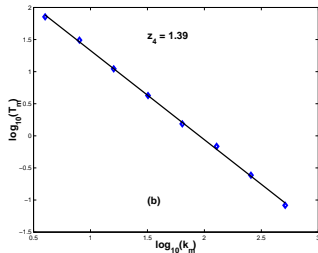
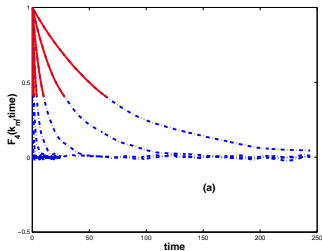
Dynamics of Kraichnan model

- Generalization to higher order is possible but messy.
- Eulerian time-dependent structure functions have no good limit due to sweeping, diverges as L^ξ .
- Quasi-Lagrangian time-dependent structure functions remain finite, shows exponential decay in time, and simple dynamic scaling:

$$z^{ql} = 2 - \xi$$

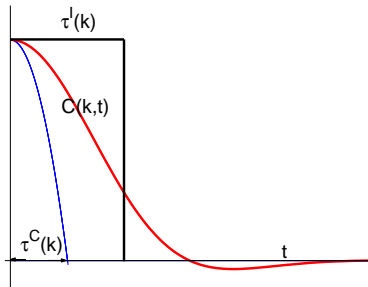
- Same dynamic scaling can be recovered by simple dimensional analysis.
- The dynamic scaling exponent bears no relationship with [zero-modes](#).

Numerics of Kraichnan-shell model



- Shell model analog of Kraichnan model.
- Dynamic exponent of 4-th order.

Varieties of time-scales



- In dynamic critical phenomenon the integral and curvature time has the same scaling properties. More generally the dynamic scaling property does not depend on **how** you define the time scale.

$$\tau^C \sim \tau^I \sim k^{-z} \sim r^z$$

Varieties of dynamic multiscaling

- Integral time scale

$$\mathcal{T}_p^I(\ell) \equiv \frac{1}{\mathcal{S}_p(\ell)} \int_0^\infty \mathcal{F}_p(\ell, t) dt \sim \ell^{z_{p,1}^I}$$

- Curvature time scale

$$\mathcal{T}_{p,2}^D(\ell) \equiv \left[\frac{1}{\mathcal{S}_p(\ell)} \frac{\partial^2}{\partial t^2} \mathcal{F}_p(\ell, t) dt \right]^{(-1/2)} \sim \ell^{z_{p,2}^D}$$

- Using the multifractal model we derive the **bridge relations**

$$z_{p,1}^I = 1 + [\zeta_{p-1} - \zeta_p],$$

$$z_{p,2}^D = 1 + [\zeta_p - \zeta_{p+2}]/2.$$

Multifractal Derivation for Integral Scale

$$\mathcal{F}_p(\ell, t) \propto \int_{\mathcal{I}} d\mu(h) \left(\frac{\ell}{L}\right)^{Z(h)} \mathcal{G}^{p,h}\left(\frac{t}{\tau_{p,h}}\right),$$

where $\mathcal{G}^{p,h}\left(\frac{t}{\tau_{p,h}}\right)$ has a characteristic decay time

$\tau_{p,h} \sim \ell/\delta v(\ell) \sim \ell^{1-h}$, and $\mathcal{G}^{p,h}(0) = 1$. If $\int_0^\infty t^{(M-1)} \mathcal{G}^{p,h} dt$ exists,

$$\begin{aligned} \mathcal{T}_{p,1}^I(\ell) &\equiv \frac{1}{\mathcal{S}_p(\ell)} \int_0^\infty \mathcal{F}_p(\ell, t) dt \\ &\propto \frac{1}{\mathcal{S}_p(\ell)} \int_{\mathcal{I}} d\mu(h) \left(\frac{\ell}{L}\right)^{Z(h)} \int_0^\infty dt \mathcal{G}^{p,h}\left(\frac{t}{\tau_{p,h}}\right) \\ &\propto \left[\frac{1}{\mathcal{S}_p(\ell)} \int_{\mathcal{I}} d\mu(h) \left(\frac{\ell}{L}\right)^{p h + 3 - D(h)} \ell^{1-h} \right] \end{aligned}$$

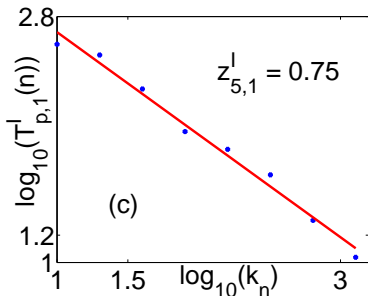
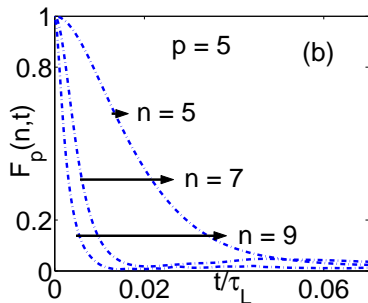
In the last step, we have used :

$$\tau_{p,h} \sim \ell/\delta v(\ell) \sim \ell^{1-h}$$

Summary

- Dynamic multiscaling is expected to be observed to Lagrangian or quasi-Lagrangian dynamic structure functions.
- There is no scale invariance of the whole dynamic structure function, scaling of a particular time-scale depends on **how** you have defined that time-scale.
- Dynamic scaling exponents can be related to the equal-time exponents by bridge relations.

Evidence from shell models



- Needs very long averaging.
- Several very serious difficulties with present computing power to do similar study in DNS of fluid turbulence.

Passive scalar model

- Using the multifractal model for passive-scalar (not white-in-time) we can derive bridge relations for the passive-scalar dynamic exponents.

$$\begin{aligned}z_{p,2}^{D,\theta} &= 1 - \zeta_2^u/2 \\z_{p,2}^{I,\theta} &= 1 - \zeta_{-1}^u\end{aligned}$$

- But we need to assume certain correlation between the velocity and the passive scalar flux.
- These predictions are expected to work for Lagrangian or quasi-Lagrangian representation for the passive-scalar.

Dynamic multiscaling in decaying turbulence

- In critical phenomenon, dynamics can be monitored by:
 - Disturbing the system away from equilibrium and looking at its approach to equilibrium.
 - Measuring time-dependent correlation function in equilibrium.
 - And these two approaches gives the same dynamic exponent.
- The analog in turbulence would be to compare dynamic exponents in forced and decaying turbulence. There is no a-priori reason why they should be equal.
- There are two ways to study decay:
 - Get the system to a non-equilibrium stationary steady state and then turn off forcing at $t = t_0$ and observe the subsequent evolution.
 - Begin from an initial state with most of the energy in large-scales, then as the system decays the cascade is completed at time $t = t_0$, observe the subsequent evolution.
- We get the same exponents from both of these methods.

Decaying dynamic structure functions

- The simplest possible form (factorisation)

$$\mathcal{F}_p^d(\ell, t_0, t) = g(t_0)\mathcal{F}_p^f(\ell, t)$$

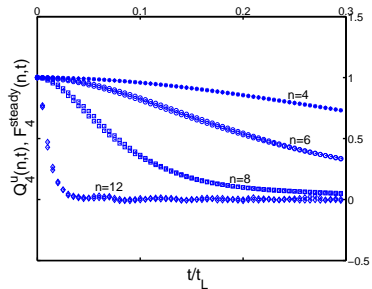
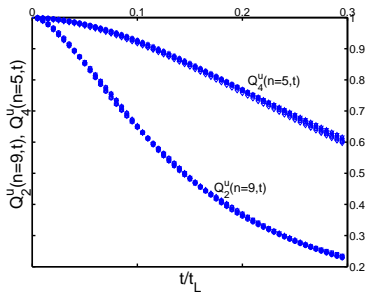
- We should then have

$$Q_p(\ell, t) \equiv \frac{\mathcal{F}_p^d(\ell, t_0, t)}{\mathcal{F}_p^d(\ell, t_0, 0)}$$

to be independent of t_0 .

- The dynamic multiscaling properties of $Q_p(\ell, t)$ is seen to be same as the dynamic multiscaling properties of $\mathcal{F}_p^f(\ell, t)$

Data from shell model



Summary

- There is strong dynamic universality in turbulence, at least in shell models of turbulence.
- Confirmed numerically in Kraichnan-shell model.
- Confirmed numerically in GOY shell model and passive-scalar shell model.
- The simplest factorisation ansatz seems to be correct.