

## Exercises 2

(1) Calculate the Frenet frame, curvature, torsion of the curve  $\gamma: t \mapsto (t, at, bt^2)$ . Verify Frenet-Serret.

$$\frac{d\gamma}{dt} = (1, a, 2bt) \quad \|\gamma'(t)\| = \frac{ds}{dt} = \sqrt{1+a^2+4b^2t^2}$$

$$T = \frac{d\gamma}{dt} \frac{dt}{ds} = \frac{(1, a, 2bt)}{\sqrt{1+a^2+4b^2t^2}}$$

$$KN = \frac{dT}{ds} = \frac{dT}{dt} \frac{dt}{ds}$$

$$= \frac{1}{\sqrt{1+a^2+4b^2t^2}} \left[ \frac{(0, 0, 2b)}{\sqrt{1+a^2+4b^2t^2}} - \frac{4b^2t(1, a, 2bt)}{\sqrt{1+a^2+4b^2t^2}^3} \right]$$

$$= \frac{1}{(1+a^2+4b^2t^2)^2} (-4b^2t, -4b^2at, 2b(1+a^2))$$

$$K = \frac{2b}{(1+a^2+4b^2t^2)^2} \sqrt{4b^2t^2(1+a^2)^2 + 4(1+a^2)^2}$$

$$= \frac{2b\sqrt{1+a^2}}{\sqrt{1+a^2+4b^2t^2}^3} \Rightarrow N = \frac{(-2bt, -2bat, 1+a^2)}{\sqrt{1+a^2}\sqrt{1+a^2+4b^2t^2}}$$

$$B \equiv T \times N = \frac{\begin{pmatrix} (1+a^2)a & -4b^2t^2 & -2bat \\ +4b^2at^2 & -(1+a^2) & +2abt \end{pmatrix}}{\sqrt{1+a^2} (1+a^2+4b^2t^2)}$$

$$= \frac{(a, -1, 0)}{\sqrt{1+a^2}}$$

$$\Rightarrow B' \equiv 0 \quad \text{so} \quad \tau \equiv 0.$$

$$\text{At } t=0 \quad T = \frac{(1, a, 0)}{\sqrt{1+a^2}} \quad N = (0, 0, 1) \quad B = \frac{(a, -1, 0)}{\sqrt{1+a^2}}$$

$$K = \frac{2b}{1+a^2} \quad \tau = 0.$$

Frenet-Serret:

$$\frac{dN}{ds} = \frac{dN}{dt} \frac{dt}{ds} = \frac{1}{\sqrt{1+a^2} \sqrt{1+a^2+4b^2t^2}} \left[ \begin{array}{l} (-2b, -2ab, 0) \cdot \frac{-4b^2t}{\sqrt{1+a^2+4b^2t^2}} \begin{pmatrix} -2bt, -2bat, 1+a^2 \end{pmatrix} \\ \hline \begin{pmatrix} -2b(1+a^2+4b^2t^2) & -2ab(1+a^2+4b^2t^2) & 0 \\ +8b^3t^2 & +8ab^3t^2 & -(1+a^2)(4b^2t^2) \end{pmatrix} \end{array} \right]$$

$$= \frac{\sqrt{1+a^2} \begin{pmatrix} -2b, -2ab, 1+4b^2t^2 \end{pmatrix}}{(1+a^2+4b^2t^2)^2}$$

$$-kT + \tau B = \frac{-2b \sqrt{1+a^2} (1, a, 2bt)}{(1+a^2+4b^2t^2)^2} + 0$$

(2) Consider the curve  $\gamma: \mathbb{R} \rightarrow \mathbb{R}^3$  given by  
$$\gamma(s) = (a \cos ws, a \sin ws, bws) \quad (\text{The Helix})$$

where  $a > 0$ ,  $b, w$  constant.

Calculate  $w$ , if  $s$  is an arc-length parameter. Calculate the Frenet frame, curvature, torsion of  $\gamma$  at an arbitrary point. Verify Frenet-Serret in this case.

Show that for suitable  $a, b$  we can find such a curve with any given constant torsion and constant positive curvature.

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$$s \text{ arclength} \Rightarrow \|\gamma'(s)\| \equiv 1.$$

$$\gamma'(s) = (-aw \sin ws, aw \cos ws, bw)$$

$$\|\gamma'(s)\| = \sqrt{a^2 w^2 + b^2 w^2} = 1$$

$$\Rightarrow w = \frac{1}{\sqrt{a^2 + b^2}}$$

$$T = (-aw \sin ws, aw \cos ws, bw)$$

$$KN = (-aw^2 \cos ws, -aw^2 \sin ws, 0)$$

$$K = aw^2 = \frac{a}{a^2 + b^2}$$

$$N = (-\cos ws, -\sin ws, 0)$$

$$B = (+bws \sin ws, -bws \cos ws, aw)$$

$$-zN = (+bw^2 \cos ws, +bw^2 \cos ws, 0)$$

$$\Rightarrow \tau = +bw^2 = \frac{+b}{a^2+b^2}$$

Frenet-Serret:  $\frac{dN}{ds} = -\kappa T + \tau B$

LHS:  $(w \sin ws, -w \cos ws, 0)$

RHS:  $(a^2 w^3 \sin ws, -a^2 w^3 \cos ws, -abw^3)$

+  $(b^2 w^3 \sin ws, -b^2 w^3 \cos ws, +abw^3)$

Note  $(a^2+b^2)w^3 = \frac{1}{w^2}w^3 = w$  so easy to verify F-S.

Finally, if  $\tau \equiv \lambda$ ,  $\kappa \equiv \mu$  for  $\lambda, \mu \in \mathbb{R}$ ,  $\mu > 0$ ,  
then we solve  $\lambda = \frac{b}{a^2+b^2}$ ,  $\mu = \frac{a}{a^2+b^2}$

to choose  $a = \frac{\mu}{\lambda^2 + \mu^2}$

$$b = \frac{\lambda}{\lambda^2 + \mu^2}$$

(3) Suppose that  $\gamma: I \rightarrow \mathbb{R}^3$  is a regular curve (not necessarily arclength parametrised). Show that:

$$\kappa = \frac{\|\gamma' \times \gamma''\|}{\|\gamma'\|^3}$$

$$\tau = \frac{(\gamma' \times \gamma'') \cdot \gamma'''}{\|\gamma' \times \gamma''\|^2}$$

Let  $s$  be the arclength parameter.

$$s = \int_{t_0}^t \|\gamma'(\tilde{t})\| d\tilde{t}$$

$$\gamma' = \frac{d\gamma}{dt} = \frac{d\gamma}{ds} \frac{ds}{dt} = T \frac{ds}{dt}$$

$$\gamma'' = \frac{d^2s}{dt^2} \frac{d\gamma}{ds} + \left(\frac{ds}{dt}\right)^2 \frac{d^2\gamma}{ds^2} = T \frac{d^2s}{dt^2} + \left(\frac{ds}{dt}\right)^2 \kappa N$$

$$\gamma''' = \frac{d^3s}{dt^3} \frac{d\gamma}{ds} + \frac{ds}{dt} \frac{d^2s}{dt^2} \frac{d^2\gamma}{ds^2} = T \frac{d^3s}{dt^3} + 3 \frac{ds}{dt} \frac{d^2s}{dt^2} \kappa N + \left(\frac{ds}{dt}\right)^3 \left[ \frac{d\kappa}{ds} N + \kappa (\kappa T + \tau B) \right]$$

$$+ 2 \frac{d^2s}{dt^2} \frac{ds}{dt} \frac{d^2\gamma}{ds^2} + \left(\frac{ds}{dt}\right)^3 \frac{d^3\gamma}{ds^3}$$

Further,  $\frac{ds}{dt} = \|\gamma'(t)\|$ ,  $\frac{d^2s}{dt^2} = \frac{\gamma' \cdot \gamma''}{\|\gamma'\|}$  [don't need!]

and  $\frac{d^3s}{dt^3} =$  [don't need!]

Now:  $\gamma' \times \gamma'' = \left(\frac{ds}{dt}\right)^3 \kappa B \Rightarrow \|\gamma' \times \gamma''\| = \|\gamma'\|^3 \kappa$

and:  $\gamma' \times \gamma'' \cdot \gamma''' = \left(\frac{ds}{dt}\right)^6 \kappa^2 \tau = \left[\left(\frac{ds}{dt}\right)^3 \kappa\right]^2 \tau = \|\gamma' \times \gamma''\|^2 \tau$

(4) Suppose that  $\beta, \gamma: I \rightarrow \mathbb{R}^3$  are two unit speed smooth curves. Suppose that the curvatures and torsions are everywhere +ve, and that  $B_\beta \equiv B_\gamma$ . Show  $\exists p \in \mathbb{R}^3$  s.t. for each  $s$ ,  $\gamma(s) = \beta(s) + p$

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$B_\beta \equiv B_\gamma$ . We differentiate:

$$\Rightarrow \tau_\beta N_\beta \equiv \tau_\gamma N_\gamma,$$

Since  $\tau_\beta, \tau_\gamma$  are both positive, we can conclude that  $\tau_\beta \equiv \tau_\gamma$  and  $N_\beta \equiv N_\gamma$ .

$$\text{Now, } T_\beta = N_\beta \times B_\beta \equiv N_\gamma \times B_\gamma = T_\gamma$$

$$\text{so } T_\beta \equiv T_\gamma.$$

Differentiating tells us that  $k_\beta N_\beta \equiv k_\gamma N_\gamma$   
and so  $k_\beta \equiv k_\gamma$ .

So by existence and uniqueness of curves with prescribed curvature and torsion, the curves  $\gamma$  and  $\beta$  agree (up to a translation).

(5) Let  $\gamma$  be a unit-speed curve with non-zero curvature and torsion.  
 Let  $r = 1/k$ ,  $t = 1/\tau$ .

Show  $\gamma$  is a spherical curve  $\Leftrightarrow r^2 + (r't)^2 \equiv R^2$

If  $\gamma \subset S^2$ ,  $\|\gamma(s) - p\|^2 = R^2$ . We differentiate:

$$\begin{aligned} (1) \quad 0 &= 2(\gamma(s) - p) \cdot \gamma'(s) \\ (2) \quad 0 &= 2\|\gamma'(s)\|^2 + 2(\gamma(s) - p) \cdot \gamma''(s) \\ (3) \quad 0 &= 2\gamma'(s) \cdot \gamma''(s) + 2\gamma'(s) \cdot \gamma''(s) + 2(\gamma(s) - p) \cdot \gamma'''(s) \end{aligned}$$

Rewriting (2):

$$0 = 2 + k^2(\gamma(s) - p) \cdot N \Rightarrow -r = (\gamma(s) - p) \cdot N$$

Rewriting (3):

$$\begin{aligned} 0 &= 2 \frac{T}{k} \cdot kN + (\gamma(s) - p) \cdot (k'N + k(-\tau B - kT)) \\ &= (\gamma(s) - p) \cdot k'N - (\gamma(s) - p) \cdot k\tau B \\ &= -rk' - k\tau(\gamma(s) - p) \cdot B \end{aligned}$$

$$\begin{aligned} \text{so } (\gamma(s) - p) \cdot B &= \frac{-rk'}{k\tau} = -r^2 k' t \\ &= -r't \end{aligned}$$

Finally from (1) we obtain  $(\gamma(s) - p) \cdot T = 0$

Recalling  $(T, N, B)$  is an orthonormal frame, we have:

$$\gamma(s) - p = [(\gamma(s) - p) \cdot T] T + [(\gamma(s) - p) \cdot N] N + [(\gamma(s) - p) \cdot B] B$$

$$\begin{aligned} \Rightarrow R^2 = \|\gamma(s) - p\|^2 &= |(\gamma(s) - p) \cdot T|^2 + |(\gamma(s) - p) \cdot N|^2 \\ &\quad + |(\gamma(s) - p) \cdot B|^2 \\ &= 0 + r^2 + (r't)^2 \end{aligned}$$

Conversely, now suppose  $r^2 + (r't)^2 \equiv R^2$  (\*)

Let  $\beta(s) = \gamma(s) + rN + r'tB$ . We will  $\beta$  is constant.

$$\beta' = \gamma' + r'N + r(\tau B - kT) + (r't' + r''t)B - \tau r'tN$$

N coefficients:  $r' - \tau r't = 0$

T coefficients:  $1 - rk = 0$

B coefficients:  $r\tau + r't' + r''t = 0$

Differentiating (\*) gives  $0 = 2r \cdot r' + 2r't(r't' + r''t)$

That is,  $(r't' + r''t) = \frac{-2rr'}{2r't} = -r\tau$

So we have  $\beta' \equiv 0 \Rightarrow \gamma(s) - p = -rN - r'tB$

$$\Rightarrow \|\gamma(s) - p\|^2 = r^2 + (r't)^2 = R^2$$