

Dynamical Systems (MA424)

1. For $x, y \in [a_0, \dots, a_{n-1}]$ we have that $x_i = y_i (= a_i)$ for $i = 0, \dots, n-1$. In particular, $d'_\lambda(x, y) \leq (n-1) \sum_{i=0}^{n-1} \lambda^{-i} = \frac{(n-1)\lambda^{-n}}{1-\lambda^{-1}}$
 $= \lambda^{-n} \left(\frac{n-1}{1-\lambda^{-1}} \right) < \lambda^{-n}$. Conversely, if $d'_\lambda(x, y) < \lambda^{-n}$ then $x_i = y_i$ for $i = 0, \dots, n-1$, i.e., they lie in the same n -cylinder.

2. By definition, $x, y \in [a_0, \dots, a_{n-1}] \Leftrightarrow d''_\lambda(x, y) = \lambda^{-n}$.
 Thus $y \in B_{d''_\lambda}(x, \lambda^{-n})$.

3. Since $|d'_\lambda| \leq \frac{n-1}{1-\lambda^{-1}}$ and $|d''_\lambda| \leq 1$ we can choose the corresponding sensitivity constant Δ to be any smaller value (i.e., given a sequence x we can always choose a nearby sequence whose distance eventually differs by this constant.)

4. We can explicitly $\pi: \Sigma_n \rightarrow \Sigma_m$ by $\pi(x_i) = (y_i)$
 where $y_i = \begin{cases} x_i & \text{if } x_i \in \{1, \dots, m\} \\ m & \text{if } x_i \in \{m+1, \dots, n\} \end{cases}$

This is easily seen to be a semi-conjugacy.

5. We explicitly define $\pi: \Sigma_A \rightarrow \Sigma_{A'}$ by $\pi(x_i) = (y_i)$ where

$$y_i = \begin{cases} 1 & \text{if } x_i = 1 \text{ and } x_{i+1} = 2 \\ 2 & \text{if } x_i = 2 \text{ and } x_{i+1} = 1 \\ 3 & \text{if } x_i = 1 \text{ and } x_{i+1} = 1. \end{cases}$$