

## MA 243 HOMEWORK 2

### SOLUTIONS

#### B: EXERCISES

- (1) Let  $T : \mathbb{E}^n \rightarrow \mathbb{E}^n$  be a motion. Fix a choice of coordinates  $\phi : \mathbb{E}^n \rightarrow \mathbb{R}^n$ .
- (a) **Show that  $\phi \circ T : \mathbb{E}^n \rightarrow \mathbb{R}^n$  is another choice of coordinates.** Since  $\phi$  and  $T$  are both bijections, their composition is as well. In addition,  $|\phi \circ T(P) - \phi \circ T(Q)| = d(T(P), T(Q)) = d(P, Q)$ , so  $\phi \circ T$  is distance preserving, and is thus a choice of coordinates.
- (b) **Define  $T' : \mathbb{R}^n \rightarrow \mathbb{R}^n$  by  $T' = \phi \circ T \circ \phi^{-1}$ . Show that  $T'$  is a distance preserving map (so  $|T'(\mathbf{x}) - T'(\mathbf{y})| = |\mathbf{x} - \mathbf{y}|$ ).**  
We have  $|T'(\mathbf{x}) - T'(\mathbf{y})| = |\phi \circ T \circ \phi^{-1}(\mathbf{x}) - \phi \circ T \circ \phi^{-1}(\mathbf{y})|$ . Since  $\phi$  is distance preserving, this equals  $d(T \circ \phi^{-1}(\mathbf{x}), T \circ \phi^{-1}(\mathbf{y}))$ . Since  $T$  is a motion, this is  $d(\phi^{-1}(\mathbf{x}), \phi^{-1}(\mathbf{y}))$ . Again, since  $\phi$  is distance-preserving, this equals  $|\mathbf{x} - \mathbf{y}|$  as required.
- (c) **Show that if  $\psi : \mathbb{E}^n \rightarrow \mathbb{R}^n$  is another choice of coordinates, then  $T : \mathbb{E}^n \rightarrow \mathbb{E}^n$  defined by  $T = \phi^{-1} \circ \psi$  is a motion.** We have  $d(T(P), T(Q)) = d(\phi^{-1} \circ \psi(P), \phi^{-1} \circ \psi(Q)) = d(\psi(P), \psi(Q)) = d(P, Q)$ , where the second equality is because  $\phi$  is distance preserving, and the third is because  $\psi$  is.
- (2) Let  $T$  be motion obtained by rotating by  $\theta$  anti-clockwise about a point  $P$  in  $\mathbb{E}^2$ , and let  $S$  be the motion obtained by rotating by  $\omega$  anti-clockwise about the same point  $P$ . Write down the matrices  $A$  and  $B$  for  $T$  and  $S$  in some choice of coordinates.

$$A = \begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix} \quad B = \begin{pmatrix} \cos(\omega) & -\sin(\omega) \\ \sin(\omega) & \cos(\omega) \end{pmatrix}.$$

Describe the motion  $T \circ S$  geometrically, and write down its matrix in the same choice of coordinates. The

motion  $T \circ S$  is rotation by  $\theta + \omega$  anti-clockwise. Its matrix is:

$$\begin{pmatrix} \cos(\theta + \omega) & -\sin(\theta + \omega) \\ \sin(\theta + \omega) & \cos(\theta + \omega) \end{pmatrix}.$$

**Compare this to the matrix  $AB$  (unsimplified) and explain your answer.**

$$AB = \begin{pmatrix} \cos(\theta)\cos(\omega) - \sin(\theta)\sin(\omega) & -\cos(\theta)\sin(\omega) - \sin(\theta)\cos(\omega) \\ \cos(\theta)\sin(\omega) + \sin(\theta)\cos(\omega) & \cos(\theta)\cos(\omega) - \sin(\theta)\sin(\omega) \end{pmatrix}.$$

The equality of the two previous matrices follows from the trigonometric angle-sum formula.

- (3) **Let  $T$  be the motion of  $\mathbb{E}^2$  of anti-clockwise rotation by  $\pi/2$  about a point  $P$ , and let  $S$  be the motion of  $\mathbb{E}^2$  of anti-clockwise rotation by  $\pi/2$  about a point  $Q$  distance one from  $P$ . Fix a coordinate choice in which  $P$  is taken to  $(0, 0)$ , and  $Q$  is taken to  $(1, 0)$ .**

- (a) **Write down the expression for  $T$  in these coordinates.**

$$T(\mathbf{x}) = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \mathbf{x}.$$

- (b) **Write down the expression for  $S$  in *these* coordinates.**

$$S(\mathbf{x}) = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \mathbf{x} + \begin{pmatrix} 1 \\ -1 \end{pmatrix}.$$

- (c) **Write down the composition  $S \circ T$  in these coordinates**

$$S \circ T(\mathbf{x}) = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} \mathbf{x} + \begin{pmatrix} 1 \\ -1 \end{pmatrix}.$$

- (d) **Describe  $S \circ T$  geometrically.** Rotation by  $\pi$  about the point  $(1/2, -1/2)$ .