Stability analysis of perturbed plane Couette flow

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Plane Couette flow perturbed by a spanwise oriented ribbon, similar to a configuration investigated experimentally at the Centre d’Études de Saclay, is investigated numerically using a spectral-element code. Two-dimensional (2-D) steady states are computed for the perturbed configuration; these differ from the unperturbed flows mainly by a region of counter-circulation surrounding the ribbon. The 2-D steady flow loses stability to three-dimensional (3-D) eigenmodes at Re = 230, βc = 1.3 for ρ = 0.086 and Re ≈ 550, βc ≈ 1.5 for ρ = 0.043, where β is the spanwise wave number and 2ρ is the height of the ribbon. For ρ = 0.086, the bifurcation is determined to be subcritical by calculating the cubic term in the normal form equation from the time series of a single nonlinear simulation; steady 3-D flows are found for Re as low as 200. The critical eigenmode and nonlinear 3-D states contain streamwise vortices localized near the ribbon, whose streamwise extent increases with Re. All of these results agree well with experimental observations. © 1999 American Institute of Physics. [S1070-6631(99)00305-0]

I. INTRODUCTION

It is well known that, of the three shear flows most commonly used to model transition to turbulence, plane Poiseuille flow is linearly unstable for Re > 5772, whereas pipe Poiseuille flow and plane Couette flow are linearly stable for all Reynolds numbers; see, e.g., Ref. 1. Yet, as is also well established, in laboratory experiments, plane and pipe Poiseuille flows actually undergo transition to three-dimensional (3-D) turbulence for Reynolds numbers on the order of 1000. For plane Couette flow, the lowest Reynolds numbers at which turbulence can be produced and sustained has been shown to be between 300 and 400 both in numerical simulations and in experiments.

The gap between steady, linearly stable flows which depend on only one spatial coordinate and three-dimensional turbulence can be bridged by studying perturbed versions of Couette and Poiseuille flow. Plane Couette flow perturbed by a wire midway between the bounding plates and oriented in the spanwise direction has been the subject of laboratory experiments by Dauchot and co-workers at CEA-Saclay. Our goal in this paper is to study numerically the flows and transitions in a configuration similar to that of the Saclay experiments.

Previous studies of plane channel flows have used a variety of approaches. We briefly review these, emphasizing computational investigations and the plane Couette case.

One approach is to seek finite amplitude solutions at transition Reynolds numbers and to understand the dynamics of transition in terms of these solutions. Finite amplitude solutions for plane Couette flow have been found for Reynolds numbers as low as Re = 125 by numerically continuing steady states or traveling waves from other flows: the wavy Taylor vortices of cylindrical Taylor–Couette flow by Nagata and Conley and Keller, and the wavy rolls of Rayleigh–Bénard convection by Busse. Most recently, Cherhabili and Ehrenstein succeeded in continuing plane-Poiseuille-flow solutions to plane Couette flow, via an intermediate Poiseuille–Couette family of flows. They showed that in proceeding from Poiseuille to Couette flow, the wave speed of the traveling waves decreases and their streamwise wavelength increases, as does the number of harmonics needed to capture them. When the Couette limit is reached, the finite amplitude solutions are highly streamwise-localized steady states. The minimum Reynolds number achieved in these continuations is Re = 1500. None of these steady solutions of plane Couette flow obtained so far are stable.

A second, highly successful, approach has been to study the transient evolution of linearized plane Couette flow. Although all initial conditions must eventually decay and the most slowly decaying mode must be spanwise invariant by Squire’s theorem, the non-normality of the evolution operator allows large transient growth. Butler and Farrell showed that a 1000-fold growth in energy could be achieved from an initial condition resembling streamwise vortices which are approximately circular and streamwise invariant. Reddy and Henningson computed the maximum achievable growth for a large range of Reynolds numbers. An interpretation is given by these authors and by Trefethen et al. in terms of pseudospectra: the spectra of non-normal operators display an extreme sensitivity to perturbations of the operator. Thus, slightly perturbed plane Couette or Poiseuille flows may be linearly unstable for much lower Reynolds numbers than the unperturbed versions.

A third broad category of computational investigation is the study of nonlinear temporal evolution in relatively tame turbulent plane channel flows. Orszag and Kells and
Orszag and Patera\textsuperscript{19} showed that finite amplitude spanwise-invariant states of plane Poiseuille flow are unstable to 3-D perturbations; this is also true of quasiequilibria for plane Poiseuille and Couette flow. Lundbladh and Johansson\textsuperscript{2} showed that turbulent spots evolved from initial disturbances resembling streamwise vortices if the Reynolds number exceeded a critical Reynolds number between 350 and 375. Numerical simulations by Hamilton, Kim, and Waleffe\textsuperscript{3} of turbulent plane Couette flow at Re = 400 indicated that streamwise vortices and streaks played an important role in a quasicyclic regeneration process. Coughlin\textsuperscript{20} used weak forcing to stabilize steady states containing streamwise vortices and streaks. These became unstable and underwent a similar regeneration cycle when the forcing or Reynolds number was increased. The critical Reynolds numbers displayed in all of these numerical simulations are in good agreement with experiments by Tillmark and Alfredsson\textsuperscript{4} and by Daviaud \textit{et al.}\textsuperscript{5} who reported turbulence at Re \(\approx 360\) and Re \(\approx 370\), respectively.

The last approach we discuss, and the most relevant to this study, is perturbation of the basic shear profile, to elicit instabilities that are in some sense nearby. If a geometric perturbation breaks either the streamwise or spanwise invariance of the basic profile, then the flow is freed from the constraint of Squire’s theorem, which would otherwise imply that the linear instability at lowest Reynolds number is to a spanwise invariant two-dimensional (2-D) eigenmode. A perturbed flow with broken symmetry may directly undergo a 3-D linear instability. One can hope to understand the behavior of the unperturbed system by considering the limit in which the perturbation goes to zero. For some time, experimentalists\textsuperscript{21} have used perturbations to produce spanwise-invariant Tollmien–Schlichting waves arising subcritically. More recently, for example, Schatz \textit{et al.}\textsuperscript{22} inserted a periodic array of cylinders in a plane Poiseuille experiment to render this bifurcation supercritical. In plane Couette flow, Dauchot and co-workers at Saclay\textsuperscript{6–8} found that streamwise vortices could be induced for Reynolds numbers around 200 when a wire was placed in the flow (the exact range in Reynolds number for which the vortices occur depends on the radius of the wire). They suspected that these vortices arise from a subcritical bifurcation from the perturbed profile, but did not determine this.

In this paper, we numerically study the destabilization of plane Couette flow when a ribbon is placed midway in the channel gap (Fig. 1). The ribbon is infinitely thin in the streamwise \((x)\) direction, occupies a fraction \(\rho\) of the cross-channel \((y)\) direction, and is infinite in the spanwise \((z)\) direction. This geometry is similar, though not identical, to that used in the Saclay experiments. In the experiments, the perturbation is a thin wire with cylindrical cross section. Here we use a ribbon because it is much easier to simulate numerically. For the experimental or numerical results to be of wider importance, the particular shape of the perturbation should not be important, as long as it is small.

We shall address the extent to which a small geometric perturbation of the plane Couette geometry affects the stability of the flow. We will show that a small geometric perturbation does indeed lead to a subcritical bifurcation to streamwise vortices, at Reynolds numbers and wave numbers which agree well with the Saclay experiments.

\section*{II. NUMERICAL COMPUTATIONS}

The computations consist of three parts: (1) obtaining steady 2-D solutions of the Navier–Stokes equations, (2) determining the linear stability of these solutions to 3-D perturbations, and (3) classifying the bifurcation via a nonlinear stability analysis. Here we outline the numerical techniques for carrying out these computations.

\subsection*{A. 2-D steady flows}

Our computational domain has been shown in Fig. 1. We nondimensionalize lengths by the channel half-height \(h\), velocities by the speed \(U_0\) of the upper channel wall, time by the convective time \(h/U_0\). There are two nondimensional parameters for the flow, which we take to be the usual Reynolds number for plane Couette flow, \(Re = hU_0/\nu\), where \(\nu\) is the kinematic viscosity of the fluid, and the nondimensional half-height of the ribbon \(\rho\), hereafter called its radius for consistency with the Saclay experiments. We view the (nondimensionalized) streamwise periodicity length \(2L\) as a numerical parameter which we take sufficiently large that the system behaves as though it were infinite in the streamwise direction.

The fluid flow is governed by the incompressible Navier–Stokes equations:

\begin{equation}
\frac{\partial \mathbf{u}}{\partial t} = - \mathbf{(u \cdot \nabla)} \mathbf{u} - \nabla p + \frac{1}{Re} \nabla^2 \mathbf{u} \quad \text{in} \quad \Omega, \tag{1a}
\end{equation}

\begin{equation}
\nabla \cdot \mathbf{u} = 0 \quad \text{in} \quad \Omega, \tag{1b}
\end{equation}

subject to the boundary conditions:

\begin{equation}
\mathbf{u}(x - L, y) = \mathbf{u}(x + L, y), \tag{2a}
\end{equation}

\begin{equation}
\mathbf{u}(x, y = \pm 1) = \pm \tilde{\mathbf{x}}, \tag{2b}
\end{equation}
\[ \mathbf{u}(x=0,y) = 0 \quad \text{for} \quad -\rho \leq y \leq \rho, \quad (2c) \]

where \( \mathbf{u}=(u,v,w) \) is the velocity field, \( \rho \) is the nondimensionalized static pressure, and \( \Omega \) is the computational domain. The pressure \( p \), like \( \mathbf{u} \), satisfies periodic boundary conditions in \( x \).

Time-dependent simulations of these equations in two dimensions (\( w=0, \partial / \partial z=0 \)) are carried out using the spectral element program PRISM. In the spectral element method, the domain is represented by a mesh of macroelements as shown in Fig. 1. The channel height is spanned by 5 elements while the number of elements spanning the streamwise direction depends on its length: 24 elements are used for \( L=32 \) and 36 elements for \( L=56 \). The no-slip condition (2c) is enforced by setting zero velocity boundary conditions along the edges of two adjoining mesh elements: This interface defines the ribbon. If continuity were imposed enlargement of the boundary conditions on just two edges of elements in the computational domain. Within each element both the geometry and the solution variables (velocity and pressure) are represented using \( N \)th order tensor-product polynomial expansions. The collocation mesh in Fig. 1 (enlargement) corresponds to an expansion with \( N=8 \).

A time-splitting scheme is used to integrate the underlying discretized equation. \(^{26}\) Based on simulations with polynomial order \( N \) in the range 6\( \leq N \leq 12 \) and time steps \( \Delta t \) in the range \( 10^{-3} \leq \Delta t \leq 10^{-2} \) we have determined that \( N=8 \) and \( \Delta t=0.005 \) give valid results over the range of \( \text{Re} \) considered. These numerical parameter values (typical for studies of this type) have been used for most of the results reported. Each velocity component is thus represented by about 7500 scalars for \( L=32 \).

Steady flows used for our stability calculations have been obtained from simulations with Reynolds numbers in the range 100\( \leq \text{Re} \leq 600 \). In all cases, the simulations were run sufficiently long to obtain asymptotic, steady velocity fields. We shall denote these steady 2-D flows by \( \mathbf{U}(x,y) \).

**B. Linear stability analysis**

Let \( \mathbf{U}(x,y) \) be the 2-D base flow whose stability is sought. An infinitesimal three-dimensional perturbation \( \mathbf{u}'(x,y,z,t) \) evolves according to the Navier–Stokes equations linearized about \( \mathbf{U} \). Because the resulting linear system is homogeneous in the spanwise direction \( z \), generic perturbations can be decomposed into Fourier modes with spanwise wave numbers \( \beta \):

\[
\mathbf{u}'(x,y,z,t) = (\hat{u} \cos \beta z, \hat{v} \cos \beta z, \hat{w} \sin \beta z),
\]

\( p'(x,y,z,t) = \hat{p} \cos \beta z \)

or an equivalent form obtained by translation in \( z \). The vector \( \hat{\mathbf{u}}(x,y,t) = (\hat{u}, \hat{v}, \hat{w}) \) of Fourier coefficients evolves according to:

\[
\frac{\partial \hat{\mathbf{u}}}{\partial t} = -((\hat{\mathbf{u}} \cdot \nabla)\mathbf{U} - (\mathbf{U} \cdot \nabla)\hat{\mathbf{u}} - (\nabla - \beta \hat{\mathbf{z}})\hat{\mathbf{p}}
\]

\[
+ \frac{1}{\text{Re}} (\nabla^2 - \beta^2) \hat{\mathbf{u}} \quad \text{in} \ \Omega,
\]

\[
(\nabla + \beta \hat{\mathbf{z}}) \cdot \hat{\mathbf{u}} = 0 \quad \text{in} \ \Omega,
\]

where \( \nabla \), etc., are two-dimensional differential operators. Equation (4) is solved subject to homogeneous boundary conditions:

\[
\hat{\mathbf{u}}(x-L,y)=\hat{\mathbf{u}}(x+L,y),
\]

\[
\hat{\mathbf{u}}(x,y)=0, \quad \hat{\mathbf{u}}(x,y)=0 \quad \text{for} \quad -\rho \leq y \leq \rho.
\]

Equation (4) with boundary conditions (5) can be integrated numerically by the method described in Sec. II A. For fixed \( \beta \), this is essentially a two-dimensional calculation. After integrating (4)–(5) a sufficiently long time, only eigenmodes corresponding to leading eigenvalues remain. We use this to find the leading eigenvalues (those with largest real part) and corresponding eigenmodes for fixed values of \( \text{Re} \) and \( \beta \) as follows. A Krylov space is constructed based on integrating (4)–(5) over \( K=8 \) successive (dimensionless) time intervals of \( T=5 \). More precisely, we calculate the fields \( \hat{\mathbf{u}}(t), \hat{\mathbf{u}}(t+T), \ldots, \hat{\mathbf{u}}(t+(K-1)T) \) and orthonormalize these to form a basis \( v_1,v_2,\ldots,v_K \). We then define the \( K \times K \) matrix \( H_{ij} = \langle v_i, \mathbf{L} v_j \rangle \) where \( \mathbf{L} \) is the operator on the right-hand side of the linearized Navier–Stokes equations and \( \langle \rangle \) is an inner product. Approximate eigenvalues \( \sigma \) and eigenmodes \( \hat{\mathbf{u}}(x,y,z) \) are calculated by diagonalizing \( H \) and using (3) to reconstruct 3-D fields. Their accuracy is tested by computing the residual \( r = \| \sigma \hat{\mathbf{u}} - \mathbf{L} \hat{\mathbf{u}} \| \). If the eigenvalue–eigenmode pairs do not attain a desired accuracy \((r<10^{-5} \text{ for the case here})\), then another iteration is performed. The new vector is added to the Krylov space and the oldest vector is discarded. This is effectively subspace iteration initiated with a Krylov subspace. More details can be found in Refs. 22, 27, and 29.

We conclude this section by considering the effect of the streamwise periodicity length \( 2L \) on the computations. Recall that we view \( L \) as a quasineutral parameter in that we seek solutions valid for large \( L \). Figure 2 shows the dependence of the leading eigenvalue \( \sigma \) on streamwise length at \( \text{Re}=250, \beta=1.3 \) (values near the primary 3-D linear instability). It can be seen that for \( L \approx 32 \) the eigenvalue is inde-
The primary effect of the ribbon is to establish a region \(|x| \leq 3\) of positive circulation (opposing that of plane Couette flow) surrounding the ribbon. Figure 3(c) shows \(\mathbf{U} - \mathbf{U}_C\) over a larger streamwise extent. Further from the ribbon are wider regions (\(3 \leq |x| \leq 24\)) in which the deviation is weak, but has the same negative circulation as plane Couette flow.

The size of the counter-rotating region is remarkably uniform over the ribbon radii and Reynolds numbers that we have studied. We define the streamwise extent of the counter-rotating region as delimited by \(\psi(x,y=0)=0\), i.e., the \(x\) values at which the streamfunction at midheight \(y=0\) has the same value as at the channel walls \(y=\pm 1\). For \(\rho = 0.086\), the counter-rotating region varies from \(|x| \leq 2.18\) for \(\text{Re}=150\) to \(|x| \leq 3.00\) for \(\text{Re}=300\), while for \(\rho = 0.043\) the counter-rotating region varies from \(|x| \leq 2.10\) for \(\text{Re} = 150\) to \(|x| \leq 2.87\) for \(\text{Re}=600\). This insensitivity to the size of \(\rho\) is significant in light of the 2-D finite-amplitude steady states calculated by Cherhabili and Ehrenstein.\(^{13,14}\) The states found by these authors in unperturbed plane Couette flow strongly resemble that in Fig. 3. These too have a central counter-rotating region surrounded by larger regions of negative circulation. At \(\text{Re}=2200\), the counter-rotating region in their flow occupies \(|x| \leq 2.31\) (see Figs. 10 and 11 of Ref. 13, Figs. 2 and 3 of Ref. 14) The similarity between the 2-D flows for \(\rho = 0.086, \rho = 0.043\), and, effectively, \(\rho = 0\) leads us to hypothesize that our 2-D perturbed plane Couette flows are connected (via the limit \(\rho \to 0\)) to those computed by Cherhabili and Ehrenstein.

We may also quantify the intensity of the counter-circulation. One measure is the maximum absolute value of \(v\), which is attained very near the ribbon, at \((x,y) = (\pm 0.081,0)\). This value is approximately independent of Reynolds number, but decreases strongly with ribbon radius: \(v_{\text{max}} = 0.031\) for \(\rho = 0.086\) and \(v_{\text{max}} = 0.013\) for \(\rho = 0.043\).

An important qualitative feature of the flow can be seen in Figs. 3(b) and 3(c): The flow is centrosymmetric, i.e., it is invariant under combined reflection in \(x\) and \(y\), or equivalently rotation by angle \(\pi\) about the origin. It can be verified that the governing equations (1) and boundary conditions (2) are preserved by the centrosymmetric transformation:

\[
\mathbf{u}(x,y) \to -\mathbf{u}(-x,-y).
\]

The unperturbed plane Couette problem is also centrosymmetric. It is in fact symmetric under the Euclidean group \(E_1\) of translations and the “reflection” consisting of the centrosymmetric transformation (6). The ribbon in the perturbed flow breaks the translation symmetry, but leaves the centrosymmetry intact. Note that reflections in \(x\) or \(y\) alone are not symmetries of either the unperturbed or the perturbed plane Couette problem because either reflection alone reverses the direction of the channel walls, violating the boundary conditions (2b).

In Fig. 4 we present streamwise velocity profiles near the ribbon. For \(|x| > 0.5\), the Couette profile is very nearly recovered. Figure 4(b) shows streamwise velocity profiles of the deviation from the linear Couette profile across the full chan-
deviation falls sharply and approximately exponentially in \( E \) the energy per unit length.

For \( u \) near \( 56 \), abrupt changes in slope at \( u \approx 23.78 \) terminating the outer region of negative circulation can also be seen in Fig. 5. The precision of the computations is surpassed beyond \( |x| = 40 \). Figure 5 shows that for \( |x| > 32 \) the deviation of the base flow from Couette is indeed very weak and this supports our choice of \( L = 32 \) as an adequate domain size for most computations.

B. 3-D linear stability results

The two-dimensional steady flows just discussed become linearly unstable to three-dimensional perturbations when the Reynolds number exceeds a critical value \( R_{\text{e}} \). To determine this value and the associated wave number, we have performed a linear stability analysis of the steady flows via the procedure described in Sec. II.B.

Figure 6 shows the growth rate \( \sigma \) of the most unstable three-dimensional eigenmode \( \mathbf{\beta} \) as a function of \( \text{Re} \) and spanwise wave number \( \beta \) for a ribbon with \( \rho = 0.086 \). For each value \( \text{Re} \), we have fit a piecewise-cubic curve, shown in Fig. 6, through the eigenvalue data to determine the wave number \( \beta_{\text{max}}(\text{Re}) \) which maximizes \( \sigma \). The critical Reynolds number \( \text{Re}_{\text{c}} \) is then determined by linear interpolation of \( \sigma[\beta_{\text{max}}(\text{Re}), \text{Re}] \) through these maxima and finding its zero crossing. From this we find critical values for the onset of linear instability to be \( \text{Re}_{\text{c}} = 230 \) and \( \beta_{\text{c}} = 1.3 \) for the ribbon with \( \rho = 0.086 \). These values are consistent with what is seen experimentally, but we delay discussion until the conclusion.

Figure 7 shows similar eigenvalue spectra for a ribbon half as large: \( \rho = 0.043 \). The critical wave number \( \beta_{\text{c}} \approx 1.5 \) is only slightly larger than the previous value. However, the critical Reynolds number is much larger: \( \text{Re}_{\text{c}} \approx 550 \). The

\[
\sigma(\beta, \text{Re}) = \text{Re}_{\text{c}}(\beta_{\text{c}}) - \beta^2
\]

for \( \beta < \beta_{\text{c}} \) and

\[
\sigma(\beta, \text{Re}) = \text{Re}_{\text{c}}(\beta_{\text{c}}) - (\beta_{\text{c}}^2 - \beta^2)
\]

for \( \beta > \beta_{\text{c}} \).

\[
E(\mathbf{U} - \mathbf{U}_C) = \int_{-L}^{L} dy \frac{1}{2} |\mathbf{U}(x, y) - \mathbf{U}_C(y)|^2
\]

as a function of \( x \) for \(-56 \leq x \leq 56\). The data show a narrow central region, corresponding to the region \( |x| \approx 2.76 \) of positive circulation seen in Fig. 3(b), where the deviation falls sharply and approximately exponentially in \( x \). For \( |x| > 2.76 \), the deviation, while very small, decays very slowly (and not exponentially) with \( |x| \). The boundaries \( x = \pm 23.78 \) terminating the outer region of negative circulation can also be seen in Fig. 5. The precision of the computations is below the precision of the computations.

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critical Reynolds number must increase as \( \rho \) is decreased since, when no ribbon is present, the problem reduces to classical plane Couette flow which is linearly stable for all finite \( \text{Re} \), i.e., \( \lim_{\rho \to 0} \text{Re}_c(\rho) = \infty \).

We note that Cherubini and Ehrenstein\(^{14}\) also calculate 3-D instability for their 2-D finite amplitude plane Couette flows. Despite the resemblance of their 2-D flows to ours, the spanwise wave number corresponding to maximal growth is much larger in their case: \( \beta \approx 23 \).

A computed eigenvector \( \vec{\mathbf{u}} = (\vec{u}, \vec{v}, \vec{w}) \) is shown in Figs. 8 and 9. This eigenvector is near marginal: \( \text{Re} = 250 \), close to \( \text{Re}_c = 230 \). The spanwise wavelength is \( \lambda = \lambda_c = 2\pi/\beta_c = 4.83 \). The other parameters are \( \rho = 0.086 \) and \( L = 32 \).

Figure 8 shows \( (\vec{u}, \vec{w}) \) velocity plots at four streamwise locations. In the \( x = 0 \) plane containing the ribbon, the flow is reflection symmetric in \( y \), and the flow is primarily spanwise. The trigonometric dependence in \( z \) with the choice of phase (3) can be seen. In the planes \( x = 1 \), \( x = 2 \), and \( x = 3 \), two counter-rotating streamwise vortices are present. The flow for negative \( x \) is obtained by reflection in \( y \).

Figure 9 presents two complementary views of the eigenvector \( \vec{u} \) for \(-1 < x < 13\). Above is a plot of \((\vec{u}, \vec{v})\) in the plane \( z = 0 \) where they are maximal [cf. Eq. (3)]. Below is a plot of \((\vec{u}, \vec{w})\) in the plane \( y = 0 \) at midchannel height.

Figure 10 shows the \( x \) dependence of the spanwise-averaged energy per unit length

\[
E(\vec{u}) = \frac{1}{\lambda_c} \int_0^{\lambda_c} \int_{-1}^{+1} dy \int_{-\infty}^{\infty} \frac{1}{2} \vec{u}^2.
\]

Here, the eigenvector was computed in a larger domain (\( L = 56 \)) in order to determine its long-range behavior. The eigenvector is localized: the energy decays exponentially with \( |x| \) and does not reflect the counter- and corotating regions of the 2-D base flow seen in Fig. 5. The flow deficit due to the ribbon produces the local minimum at \( x = 0 \).

We have also computed the vorticity of the eigenvector. Despite the streamwise vortices visible in Fig. 8, \( \omega_z \) is the smallest vorticity component and \( \omega_x \) by far the largest over most of the domain.

**C. 3-D nonlinear stability results**

Our method of nonlinear stability analysis has previously been used to determine the nature of the bifurcation to three dimensionality in the cylinder wake.\(^{28}\) The method is based on tracking the nonlinear evolution of the 3-D flow starting from an initial condition near the bifurcation at \( \text{Re}_c \).

"Near" refers both to phase space (i.e., a small 3-D perturbation from the two-dimensional profile) and to parameter space (i.e., at a Reynolds number slightly above the linear instability threshold). In essence we follow the dynamics along the unstable manifold of the 2-D steady flow far enough to determine how the nonlinear behavior deviates from linear evolution. From this we can determine very simply whether the instability is subcritical or supercritical.

Three-dimensional simulations are carried out for \( \rho = 0.086 \) at \( \text{Re} = 250 \), slightly above \( \text{Re}_c = 230 \), starting with an initial condition of the form:

\[
\mathbf{u}(x,y,z) = \mathbf{U}(x,y) + \epsilon \mathbf{u}(x,y,z),
\]

where \( \mathbf{U} \) is the 2-D base flow at \( \text{Re} = 250 \), \( \mathbf{u} \) is its eigenmode at wave number \( \beta_c = 1.3 \), and \( \epsilon \) is a small number controlling the size of the initial perturbation.

The restriction to wave numbers which are multiples of \( \beta_c \) accurately captures the evolution from initial condition (8), since the Navier–Stokes equations preserve this sub-
space of 3-D solutions. That is, we seek only to follow the evolution in the invariant subspace containing the critical eigenmode. We do not address the issue of whether the \( \lambda_c \)-periodic flow is itself unstable to long-wavelength perturbations.

To analyze the nonlinear evolution, we define the (real) amplitude \( A \) of the 3-D flow as

\[
A = \left[ \frac{1}{\lambda_c} \int_0^{+L} \int_{-1}^{+1} \int_{-L}^{+L} \frac{1}{2} |\mathbf{u}|^2 \right]^{1/2},
\]

where \( \mathbf{u}(x,y,z,t) \) is the component of the 3-D velocity field at wave number \( \mathbf{B}_c \), i.e., \( A \) is the square root of the energy of the flow at wave number \( \mathbf{B}_c \). (A complex amplitude, not required here, would include the phase of the solution in the spanwise direction.)

Figure 11 shows the time evolution of \( A \) from our simulations. The value of \( \epsilon \) is such that the initial energy of the 3-D perturbation, \( \epsilon \mathbf{u} \), is \( E = A^2 = 1.66 \times 10^{-5} \); the energy of the base flow \( \mathbf{U} \) is \( E = 21.3 \).

To interpret the nonlinear evolution, consider the normal form for a pitchfork bifurcation including terms up to third order in the amplitude:

\[
\dot{A} = \sigma A + \alpha A^3.
\]

The leading nonlinear term is cubic because the 3-D bifurcation is of pitchfork type [an \( O(2) \) symmetric pitchfork bifurcation]. The Landau coefficient \( \alpha \) determines the nonlinear character of the bifurcation. If \( \alpha > 0 \), then the nonlinearity is destabilizing at lowest order and the bifurcation is subcritical; if \( \alpha < 0 \), then the cubic term saturates the instability and the bifurcation is supercritical.

Figure 11 includes curves for first-order evolution (i.e., \( \dot{A} = \sigma A \)) and the third-order evolution given by Eq. (10). For the first-order evolution, the eigenvalue \( \sigma \) for the bifurcation has been computed via the linear stability analysis in Sec. III B. For the third-order evolution we have simply fit the one remaining parameter, \( \alpha \), in the normal form. We followed the approach in Ref. 28 of using the time series \( A(t) \) and the known value of \( \sigma \) to estimate \( \alpha \) from \( \alpha = (A - \sigma A)/A^3 \). This gives \( \alpha = 0.9 \pm 0.05 \), a constant value for \( T \leq 500 \), which determines how long the third-order truncation is valid in this case. The value of \( \alpha \) is essentially unchanged when the mesh is refined by increasing the polynomial order \( \mathcal{N} \) to 10 or the number \( \mathcal{M} \) of Fourier modes to 32. The magnitude of \( \alpha \) depends on the definition of \( A \), but its sign does not. The fact that \( \alpha \) is positive indicates that the instability is subcritical. Figure 11 indicates that the 3-D flow has become steady by \( t \approx 1000 \). The nonlinear saturation seen in the time series is not captured by including a fifth-order term in the normal form.

We have verified that the instability is subcritical by computing nonlinear states below \( \text{Re}_c \). In Fig. 12, we show the steady 3-D flow at \( \text{Re} = 200 \). Figure 12 is analogous to Fig. 8 depicting the eigenvector, so we will emphasize here the ways in which the two flows differ. Small streamwise vortices can be seen in each of the four corners of the \( x = 0 \) plane containing the ribbon. The lower \(( y < 0) \) pair evolve with \( x \) into the strong pair of vortices at \( x = 1 \). The vortices at \( x = 3 \) are tilted with respect to their counterparts in the eigenvector, attesting to the nonlinear generation of the second spanwise harmonic \( 2 \mathbf{B} \). The 3-D flow in the \( y = 0 \) and \( z = 0 \) planes (after subtraction of the dominant 2-D base flow) is sufficiently similar to the eigenvector (Fig. 9) that we do not present it here.

Streamwise velocity \( u \) contours of the 3-D flow at \( x = 2 \) are shown in Fig. 13. The \(( u,v,w) \) projections of our 3-D flow in Fig. 12, showing the tilted streamwise vortices, resemble the depictions of optimally growing modes by Butler and Farrell,\(^{15} \) of instantaneous turbulent flows by Hamilton et al.\(^{13} \), and of weakly forced states by Coughlin.\(^{20} \) However, our streamwise velocity \( u \) pictured in Fig. 13 differs significantly from Refs. 3 and 20 in that their \( u \) contours are much more strongly displaced at the vortex boundaries. This is
probably due to the fact that our Reynolds number of 200 is substantially lower than their Re=400.

Far from the ribbon, the 3-D flow returns to plane Couette flow. Figure 14 compares the energy distribution $E(U - U_C)$ defined by (7) of the deviation of the 3-D flow from plane Couette flow at Re=200 with that at Re=250. Note that the 3-D flow is less localized than the corresponding eigenvector (Fig. 10). It can be seen that at the higher Reynolds number the deviation has higher energy, and importantly, occupies a larger streamwise extent. This is in accord with the experimental observation that the streamwise extent of vortices in the perturbed flow increases with increasing Reynolds number.

We have attempted to determine the location of the saddle-node bifurcation marking the lower Reynolds number limit of this branch of steady 3-D states; we believe that it occurs just below Re=200. There remains nevertheless a slight uncertainty regarding the lower bound for these states because we have found evidence of two different types of branches of steady 3-D states over the range 200<Re<250. The study of these states is further complicated by the fact that the time evolution to many of them is oscillatory, indicating that their least stable eigenvalues are a complex conjugate pair. Further investigation is required to ascertain the full nonlinear bifurcation diagram.

We have also sought to determine how the scenario changes as the ribbon radius $\rho$ is decreased. Recall from Sec. III B that for $\rho=0.043$, we found Re,$C=550$. At these parameter values, 3-D simulations display chaotic time evolution. By decreasing Re, we have succeeded in computing a stable 3-D steady state at Re$=350$. Since the simulation showed chaotic oscillation for a long time (3000 time units) before showing signs of approaching a steady state, there remains the possibility that stable 3-D steady states are also attainable for higher Re. Simulations at Re$=300$ result in decay to the basic 2-D state (although we do not exclude the possibility of maintaining 3-D states by a more gradual decrease in Re). This is consistent with simulations of the unperturbed plane Couette geometry ($\rho=0$) by Hamilton et al.,3 who observed chaotic oscillation for Re$\geq400$ and plane Couette flow $U_C = y\hat{x}$ for Re$=300$. Other numerical5 and experimental4 investigations in the unperturbed plane Couette geometry also indicate a critical Reynolds number of 360–375 for transition to turbulence. We plan to investigate the $\rho$ dependence of the steady 3-D states and their stability in a future publication.

IV. CONCLUSION

We have performed a computational linear and nonlinear stability analysis of perturbed plane Couette flow in order to understand experiments recently performed at Saclay,6-8 and more generally, three-dimensional flows in the plane Couette system. We have accurately determined the extent to which the basic steady 2-D profile is modified by the presence of a small spanwise-oriented ribbon in the flow. We have determined that such a ribbon, comparable in size to the cylinders used in the Saclay experiments, is large enough to induce linear instability of the basic profile at Reynolds numbers of order a few hundred.

We elaborate further on how our analysis complements the Saclay results. An experimental diagram was obtained7,8 for the Reynolds number range of existence of various types of flows: 2-D, 3-D with streamwise vortices, intermittent, and turbulent. In these experiments it was not determined whether the 3-D streamwise vortices arise from a linear instability of the 2-D flow. Our results show that a small geometric perturbation does destabilize the 2-D flow in a subcritical instability and that the bifurcating solution is a 3-D flow with streamwise vortices. Specifically, for a nondimensional radius $\rho=0.086$, we find Re,$C=230$ and for $\rho=0.043$, we find Re,$C=550$. The computed spanwise wavelength of the most unstable mode is in good agreement with the value seen experimentally. The streamwise extent occupied by these vortices decreases with decreasing Reynolds number, as observed in experiment, and is finite at the lower Reynolds limit of the 3-D flows.

The Reynolds number ranges for the steady 3-D flows we have computed differ somewhat from those seen experimentally. For $\rho=0.086$, streamwise vortices were observed experimentally over the range 150<Re<290. For $\rho=0.086$, we have thus far found steady 3-D flows only if Re>200. In experiments with $\rho=0.043$, streamwise vortices have been observed over the range 190<Re<310; we have thus far found steady 3-D flows only for Re near 350. However, a full study of the 3-D flows is still pending and may resolve these discrepancies.

FIG. 13. Streamwise velocity contours in the plane $x=2$ for the 3-D field. Solid contours correspond to $u>0$, dashed contours to $u<0$.

FIG. 14. Energy of deviation from plane Couette flow of 3-D velocity fields at Re=200 (dashed) and Re=250 (solid) as a function of $x$. The range in $x$ is taken larger than the computational domain ($L=32$) to match the range of Figs. 5 and 10.
There are also minor qualitative differences between our results and the experimental findings. The first is that 2-D flows in our computations are more nearly antisymmetric in the cross-channel direction \( y \) than in experiment (our Fig. 4 vs Fig. 4 of Ref. 8). This is probably due to the fact that we perturb our flow with an infinitely thin ribbon and not a wire (cylinder) as in the experiment. However, based on the existence of instability in both cases, this small difference in the basic 2-D flow is probably not very significant. The other difference is due to the fact that our 3-D simulations impose spanwise periodicity with a single critical wavelength \( \lambda_z \). Experimentally, it is observed that the streamwise vortices are not always regularly spaced in the spanwise direction.

As stated in Sec. I, streamwise vortices can be made to appear in channel flows via a number of approaches. Butler and Farrell\textsuperscript{15} and Reddy and Henningson\textsuperscript{16} show that under linear evolution, modes of this type can achieve very high amplitude before eventually being damped. In the pseudospectrum interpretation of Trefethen et al.,\textsuperscript{17,16} non-normality leads to sensitivity of the spectrum: streamwise vortices are unstable modes of a slightly perturbed linear stability matrix. Our results are entirely consistent with this interpretation: the ribbon or wire serves as a specific realization of a perturbation to the stability matrix, and has indeed rendered the flow linearly unstable to streamwise vortices.

Future computational work is needed to explore these flows. Calculating complete bifurcation diagrams for the two cases \( \rho = 0.086 \) and \( \rho = 0.043 \) is the first priority. We plan to study quantitatively and qualitatively the bifurcations at which the steady 3-D flows terminate at low Re and lose stability at high Re. Our goal is to continue 2-D and 3-D solutions of the perturbed system to the plane Couette case, \( \rho = 0 \).

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